

Semi-Nonparametric Estimation of a Nonseparable Demand Function under Shape Restrictions

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Introduction

- ▶ This paper is about semi-nonparametric quantile estimation of
 - ▶ a demand function
 - ▶ the welfare consequences of price changes.
- ▶ We motivate and illustrate our methods with an application to the demand for gasoline in the U.S.
 - ▶ Real gasoline prices in the U.S. have more than doubled over the past 10 years
 - ▶ Interest in differential price effects across the income distribution.
- ▶ Simple parametric demand functions impose strong restrictions on price-income interactions.
- ▶ This motivates the use of nonparametric methods to estimate demand.

Motivation

- ▶ The nonparametric estimate of the demand function is noisy due to random sampling errors.
 - ▶ The estimated function is volatile, nonmonotonic, and inconsistent with economic theory.
- ▶ One way of overcoming this problem is to impose further structure on the demand function
 - ▶ For example, assume that the demand function has a single-index structure.
 - ▶ But there is no guarantee from economic theory that demand has such a structure.
 - ▶ Demand estimation using a misspecified model may give seriously misleading results.

Motivation (cont.)

- ▶ This paper takes a different approach
- ▶ We impose structure on the demand function by using a shape restriction from economic theory.
- ▶ Specifically, we impose the Slutsky restriction of consumer theory on the demand function
- ▶ This approach yields well-behaved estimates of the demand function and deadweight losses.
- ▶ Our method
 - ▶ maintains the flexibility of nonparametric estimation
 - ▶ generates estimates consistent with economic theory
 - ▶ Avoids using essentially arbitrary and possibly incorrect restrictions to stabilize the estimates.

Unobserved heterogeneity and quantile estimation

- ▶ In previous work, we have investigated gasoline demand, focussing on the conditional mean (Blundell, Horowitz, Parey, 2010).
- ▶ If unobserved heterogeneity enters in a non-separable manner,
 - ▶ the conditional mean represents an average across unobservables, which may be difficult to interpret
 - ▶ under suitable restrictions, quantile estimation allows to recover demand at a specific point in the distribution of unobservables.
- ▶ This motivates our interest in a quantile estimator.

- ▶ Quantile regression also allows us to study differential effects of price changes and Deadweight Loss across the distribution of unobservables
 - ▶ compare heavy users with moderate or light users.

Outline

Description of data

Semi-nonparametric estimates

Semi-nonparametric estimation subject to Slutsky restrictions

Estimation of deadweight loss

Conclusions

Data

- ▶ Data are from the 2001 National Household Travel Survey (NHTS).
- ▶ This is a household-level survey that was conducted by telephone and complemented by travel diaries and odometer readings.
- ▶ The nonparametric estimates are shown below for the three income groups whose midpoints in 2001 dollars are \$42,500, \$57,500 and \$72,500.
 - ▶ These correspond to quartiles of the income distribution
- ▶ To minimize heterogeneity, we restrict the analysis to households with a white respondent, two or more adults, at least one child under age 16, and at least one driver.
- ▶ We take vehicle ownership as given and do not investigate how changes in gasoline prices affect vehicle purchases or ownership.
 - ▶ See Bento, Goulder, Henry, Jacobsen, and von Haefen (2005)
- ▶ The resulting sample contains 5,254 observations.
- ▶ A parametric log-log model, at the median, gives
 - ▶ a price elasticity of -0.36, and
 - ▶ an income elasticity of 0.34.

The Semi-Nonparametric Model

The demand function is

$$Q = g(P, Y, X, U)$$

To ensure identification, we assume that

- ▶ U is statistically independent of (P, Y, X) .
- ▶ g is monotone increasing in its 4th argument.
- ▶ Given these assumption, we can also assume without loss of generality that $U \sim U[0; 1]$.

Under these assumptions, the α quantile of Q conditional on (P, Y, X) is

$$Q_\alpha(Q|P, Y, X) = g(P, Y, X, \alpha) \equiv G_\alpha(P, Y, X)$$

Thus, the underlying demand function, evaluated at a specific value of the unobservable, can be recovered via quantile estimation.

In contrast, the conditional mean is

$$\begin{aligned} E(Q|P = p, Y = y, X = x) &= \int g(p, y, x, u) F(u) du \\ &= m(p, y, x) \end{aligned}$$

Imposing the constraint at a specific value of $U = \alpha$ is attractive because economic theory informs us about $g(\cdot)$ rather than $m(\cdot)$.

The Semi-Nonparametric Model

We can write

$$Q = G_\alpha(P, Y, X) + V_\alpha$$

where V_α is a random variable whose α quantile conditional on (P, Y, X) is zero. To mitigate the curse of dimensionality, we assume that G_α has a partially linear structure:

$$Q_\alpha(Q|P, Y, X) = H_\alpha(P, Y) + \beta_\alpha X$$

where β_α is a vector of constant coefficients. Thus, the estimated model for each α is

$$Q = \hat{H}_\alpha(P, Y) + \hat{\beta}_\alpha X + V_\alpha$$

where H_α is nonparametric.

Semi-Nonparametric Estimation

- ▶ We estimate H_α using B-splines:

$$H_\alpha(P, Y) = \sum_{m_1} \sum_{m_2} c_{m_1, m_2; \alpha} B_{m_1}^p(P) B_{m_2}^y(Y)$$

where B^p and B^y (with indices m_1 and m_2) are spline functions following Powell (1981), and $c_{m_1, m_2; \alpha}$ is the matrix of coefficients.

- ▶ Denote the data by $\{Q_i, P_i, Y_i, X_i : i = 1, \dots, n\}$.

The estimator is defined in the following optimization problem:

$$\min_{\{c_{m_1, m_2; \alpha}\}, \beta_\alpha} \sum_{i=1}^n \rho_\alpha(Q_i - H_\alpha(P_i, Y_i) - \beta_\alpha X_i)$$

where $\rho_\alpha(V) = (\alpha - \mathbb{1}\{V < 0\})V$ is the check function.

Semi-Nonparametric Estimation (cont.)

Implementation:

- ▶ We use cubic splines
- ▶ To avoid influence of low-density areas, we restrict attention to a price-income rectangle of interest:
 - ▶ price between \$1.22 and \$1.47
 - ▶ income between \$35,000 and \$100,000.
- ▶ Set of covariates contained in X : Public transit availability, urbanity indicators, population density indicators.
- ▶ For each quantile of interest, the number of knots is obtained by cross-validation.

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Imposing the Slutsky Condition

- ▶ We impose the Slutsky condition on the nonparametric estimate of the conditional quantile function.
- ▶ The condition is

$$\frac{\partial G_\alpha(P, Y, X)}{\partial p} + G_\alpha(P, Y, X) \frac{\partial G_\alpha(P, Y, X)}{\partial y} \leq 0.$$

- ▶ The constrained estimator is obtained by solving the problem

$$\min_{\{c_{m_1, m_2; \alpha}\}, \beta_\alpha} \sum_{i=1}^n \rho_\alpha \left(Q_i - \hat{G}_\alpha^C(P_i, Y_i, X_i) \right)$$

subject to

$$\frac{\partial \hat{G}_\alpha^C(P, Y, X)}{\partial p} + \hat{G}_\alpha^C(P, Y, X) \frac{\partial \hat{G}_\alpha^C(P, Y, X)}{\partial y} \leq 0$$

for all (P, Y, X) . This problem has uncountably many constraints.

Implementation

- ▶ We replace the continuum of constraints by a discrete set, thereby solving:

$$\min_{\{c_{m_1, m_2; \alpha}\}, \beta_\alpha} \sum_{i=1}^n \rho_\alpha \left(Q_i - \hat{G}_\alpha^C(P_i, Y_i, X_i) \right)$$

subject to

$$\frac{\partial \hat{G}_\alpha^C(p_j, y_j, x_j)}{\partial p} + \hat{G}_\alpha^C(p_j, y_j, x_j) \frac{\partial \hat{G}_\alpha^C(p_j, y_j, x_j)}{\partial y} \leq 0, \quad j = 1, \dots, J,$$

where $\{p_j, y_j, x_j : j = 1, \dots, J\}$ is a grid of points.

- ▶ To implement this, we use a method of Koenker & Ng (2004) for quantile regression subject to (linear) inequality constraints.
 - ▶ We linearize the restriction by holding $G_\alpha(P, Y, X)$ in the income effect constant at the unconstrained solution.
 - ▶ We then iterate this procedure, using the constrained estimate for $G_\alpha(P, Y, X)$ previously obtained.

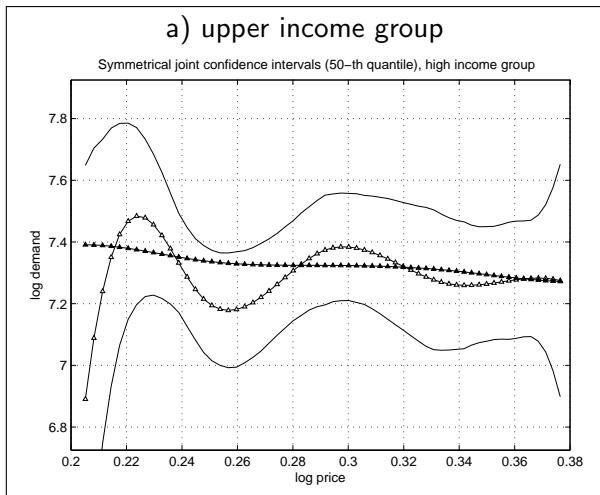
Role of partially-linear covariates in imposing the constraint

- ▶ Given the partially linear structure, the choice of the x_j , the X where we impose the constraint, may matter.
- ▶ In principle, this can make the restriction more or less binding, but we do not exploit this.
- ▶ We choose x_j as follows: At each grid point, we find the household in the data closest to that (p_j, y_j) combination.
- ▶ We set x_j equal to the covariates for that household.

Imposing the Slutsky Condition (cont.)

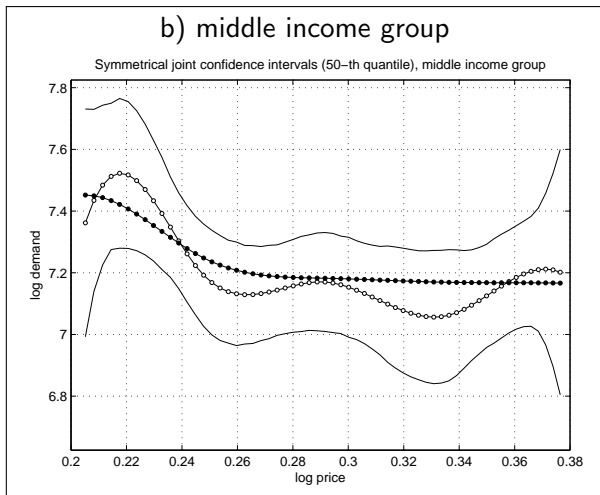
- ▶ We use the bootstrap for inference under the assumption that the Slutsky constraint does not bind in the population.
- ▶ The constrained estimates are
 - ▶ Consistent with economic theory.
 - ▶ Contained in a 90% confidence band around the unconstrained ones; consistent with random sampling error interpretation.
 - ▶ The middle income group is more sensitive to price than are the two outer groups.

Figure: Demand estimates and simultaneous confidence intervals (at $\alpha = 0.5$)



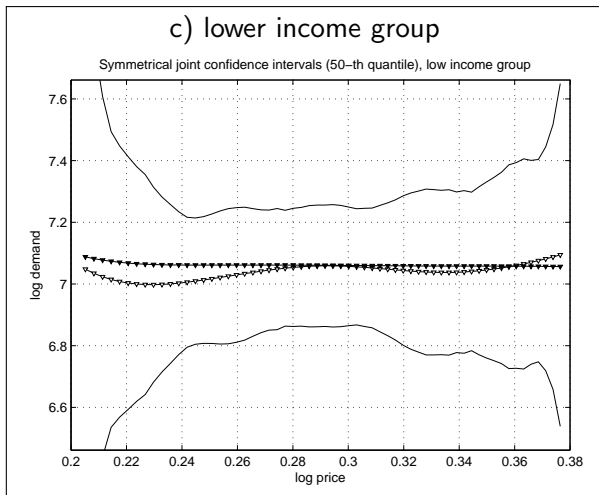
Note: Confidence intervals shown refer to bootstrapped symmetrical, simultaneous confidence intervals with a confidence level of 10%, based on 1,999 replications.

Figure: Demand estimates and simultaneous confidence intervals (at $\alpha = 0.5$)



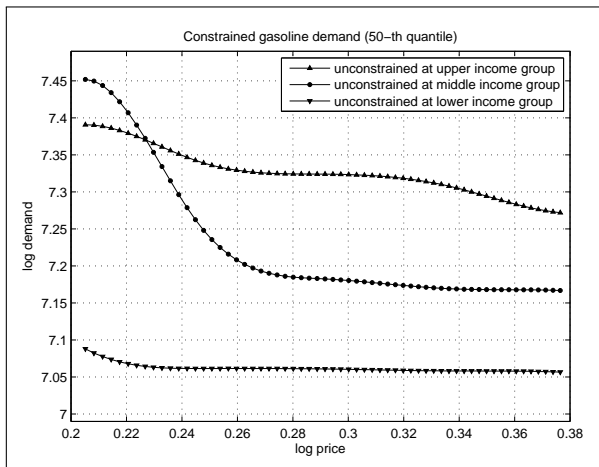
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Figure: Demand estimates and simultaneous confidence intervals (at $\alpha = 0.5$)



Note: Confidence intervals shown refer to bootstrapped symmetrical, simultaneous confidence intervals with a confidence level of 10%, based on 1,999 replications.

Figure: Summary constrained demand estimates (at $\alpha = 0.5$)



Do different income groups have different price derivatives?

- ▶ Interest in testing whether the price derivatives between two given income levels is equal.
- ▶ Null hypothesis:

$$\left. \frac{\partial G_{\alpha}(P, Y, X)}{\partial p} \right|_{Y=y^0} - \left. \frac{\partial G_{\alpha}(P, Y, X)}{\partial p} \right|_{Y=y^1} = 0$$

for all p in some interval.

- ▶ Given our specification for G_{α} , this leads to:

$$\sum_{m_1} \sum_{m_2} \frac{\partial B_{m_1}^p(p)}{\partial p} c_{m_1, m_2; \alpha} (B_{m_2}^y(y^1) - B_{m_2}^y(y^0)) = 0$$

- ▶ This implies a linear restriction on the vector of coefficients.
- ▶ We can test this using a Wald test.

Differential price effects – preliminary results

Comparison with high income group ($y_1 = \$72,500$) for unconstrained median estimates:

| income (y_0) | p -value |
|--------------------------------|------------|
| middle income group (\$57,500) | 0.0442 |
| lower income group (\$42,500) | 0.4143 |

Note: Cubic splines with 5 knots in price and 2 knots in income dimension. Unconstrained variance-covariance matrix is bootstrapped (999 replications).

- ▶ Evidence of differential price effects across the income distribution.

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Estimating Deadweight Loss (DWL)

- ▶ Let $e(p)$ denote the expenditure function at price p and some reference utility level (keeping X implicit).
- ▶ The DWL of a tax that changes the price from p^0 to p^1 is

$$L(p^0, p^1) = e(p^1) - e(p^0) - (p^1 - p^0) G_\alpha [p^1, e(p^1), X].$$

- ▶ We estimate $L(p^0, p^1)$ by replacing e and g with consistent estimates.
- ▶ The estimator of e , \hat{e} , is obtained by numerical solution of the differential equation

$$\frac{d\hat{e}(t)}{dt} = \hat{G}_\alpha [p(t), \hat{e}(t), X] \frac{dp(t)}{dt},$$

where $[p(t), \hat{e}(t)]$ ($0 \leq t \leq 1$) is a price-(estimated) expenditure path.

| <i>DWL (as % of tax paid)</i> | | | |
|-------------------------------|--------------------|-------------|------------|
| | Semi-nonparametric | | Parametric |
| | unconstrained | constrained | log-log |
| Income | (1) | (2) | (3) |

Panel A: 75th-percentile

| | | | |
|----------|----------|--------|--------|
| \$72,500 | -1.23 % | 3.63 % | 2.02 % |
| \$57,500 | 4.42 % | 8.35 % | 2.01 % |
| \$42,500 | -13.12 % | 0.34 % | 1.99 % |

Panel B: 50th-percentile

| | | | |
|----------|---------|--------|--------|
| \$72,500 | 2.67 % | 5.63 % | 3.06 % |
| \$57,500 | 0.61 % | 6.37 % | 3.04 % |
| \$42,500 | -5.45 % | 0.54 % | 3.02 % |

Panel C: 25th-percentile

| | | | |
|----------|---------|---------|--------|
| \$72,500 | 3.56 % | 6.34 % | 6.17 % |
| \$57,500 | 23.31 % | 13.85 % | 6.16 % |
| \$42,500 | 52.65 % | 45.73 % | 6.14 % |

- ▶ Some unconstrained estimates of DWL have the incorrect sign
- ▶ The nonparametric estimates show a strong dependence of DWL on income.
- ▶ Parametric estimates are very different from the nonparametric ones and do not show the income dependence of DWL measures.

Conclusions

- ▶ Simple parametric models of demand functions can be misspecified and, consequently, yield misleading estimates of price sensitivity and DWL.
- ▶ Nonparametric estimates eliminate the risk of specification error but can be poorly behaved (e.g., non-monotonic) due to random sampling errors.
- ▶ This paper has shown that these problems can be overcome by constraining nonparametric estimates to satisfy the Slutsky condition of economic theory.
 - ▶ This stabilizes the nonparametric estimates without the need for essentially arbitrary parametric or semiparametric restrictions that have no theoretical basis.
- ▶ We have illustrated this approach by estimating a gasoline demand function.
 - ▶ Fully nonparametric estimates are nonmonotonic and violate consumer theory
 - ▶ The constrained estimates are well-behaved and reveal features not found with parametric model

Conclusions (2)

- ▶ We have also estimated deadweight losses of some tax increases
 - ▶ The unconstrained nonparametric estimates sometimes have incorrect signs.
 - ▶ The constrained nonparametric estimates have correct signs and are very different from those obtained from a simple parametric model.
 - ▶ The constrained nonparametric estimates reveal patterns of income dependence that are not present in the parametric estimates
- ▶ Further research:
 - ▶ Estimate Slutsky-constrained models in which prices may be endogenous, with the distance variable we have previously used to instrument for P .
 - ▶ Estimate systems of demand functions for several goods