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## Lecture 5b

# Testing for Jumps in a Discretely Observed Process: Low Frequency

Yacine Aït-Sahalia  
Princeton University

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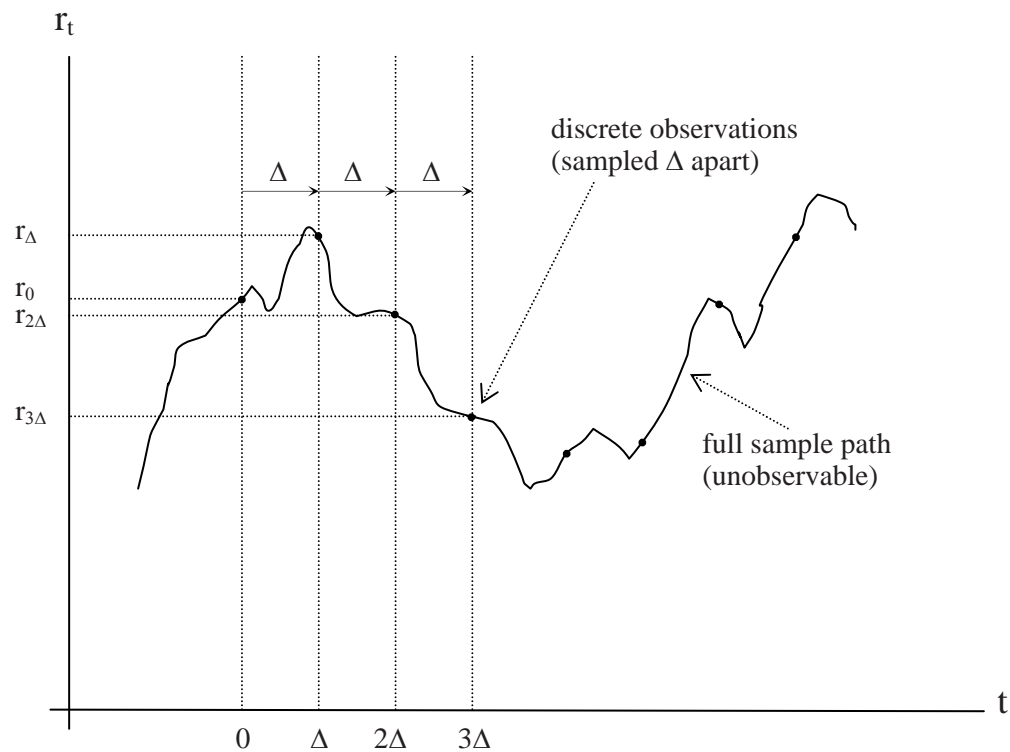
## References

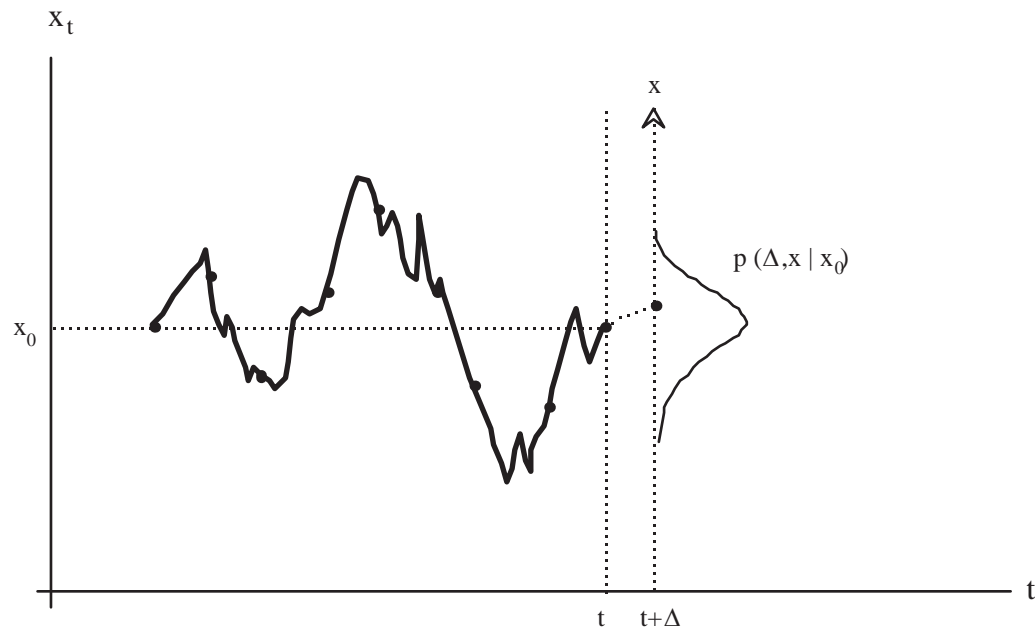
- Telling From Discrete Data Whether the Underlying Continuous-Time Model is a Diffusion, *Journal of Finance*, 2002, 57, 2075-2112.

# 1. Introduction

- Assume that  $X$  is a Markov process.
- Does the process belong to the smaller class of diffusions? That is, does it have continuous sample paths?
- How can we answer that question if we only sample  $X$  discretely, and, to compound the problem, not necessarily at high frequency?

Transition function:  $p(\Delta, y|x)$  is the conditional density of  $X_{t+\Delta} = y$  given  $X_t = x$





## 2. Example

- Suppose that we have found empirically that discrete interest rate data approximately follow:

$$r_{t+\Delta}|r_t \sim \mathcal{N}(\gamma_0 + \gamma_1 r_t, \delta_0^2)$$

- We can then construct a continuous-time diffusion:

$$dr_t = \beta(\alpha - r_t)dt + \sigma dZ_t$$

- For which  $p(\Delta, y|x)$  is Gaussian with:

$$E[r_{t+\Delta}|r_t] = r_t + (\alpha - r_t)e^{-\beta\Delta}$$
$$V[r_{t+\Delta}|r_t] = \frac{\sigma^2}{2\beta}(1 - e^{-2\beta\Delta})$$

- Now set:

$$\beta = -\text{Ln}(1 - \gamma_1) / \Delta$$

$$\alpha = \gamma_0 / (1 - \gamma_1)$$

$$\sigma^2 = -2\delta_0^2 \text{Ln}(1 - \gamma_1) / ((1 - \gamma_1)^2 \Delta)$$

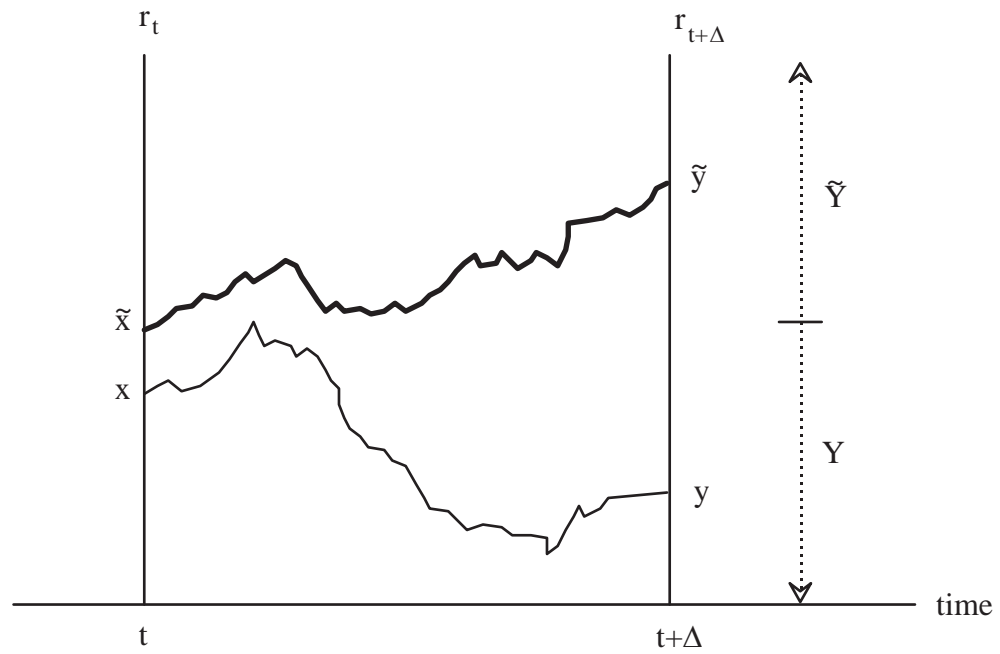
- The continuous-time diffusion  $dr_t = \beta(\alpha - r_t)dt + \sigma dW_t$  is fully determined
- Unfortunately, such calculations are impossible to conduct in most cases!

### 3. Geometric Implication of the Continuity of Sample Paths

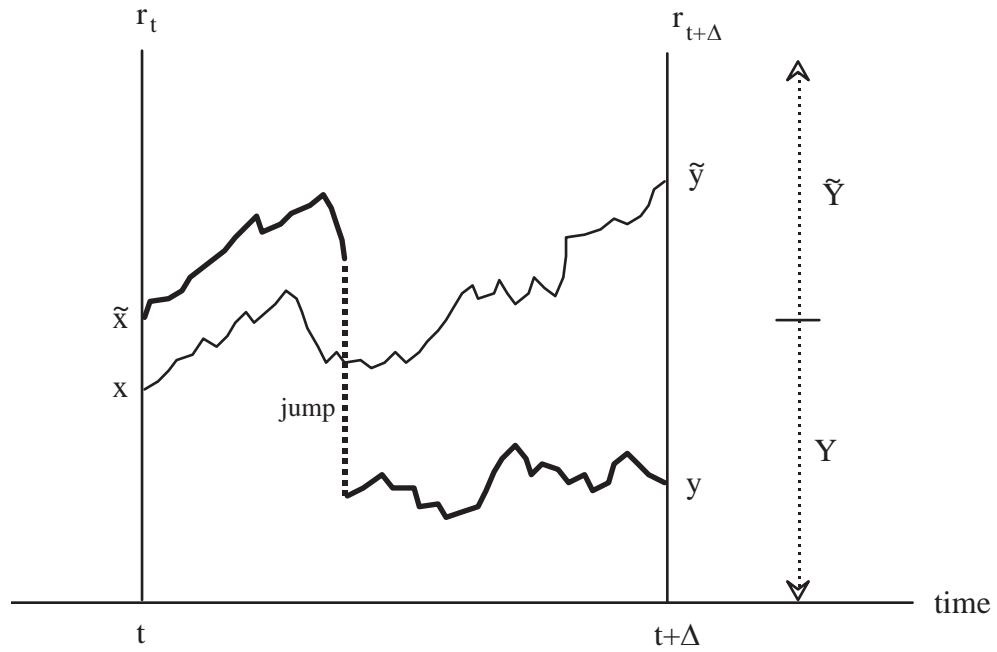
- Consider two processes  $\{r_t, t \geq 0\}$  and  $\{\tilde{r}_t, t \geq 0\}$  on  $\mathbb{R}$  with the same distribution, starting at  $r_t = x$  and  $\tilde{r}_t = \tilde{x}$  with  $x < \tilde{x}$ .
- If the process has continuous sample paths, then at any future date  $t + \Delta$ , the process  $r$  cannot be above  $\tilde{r}$  without their sample paths having crossed at least once.



### 3 GEOMETRIC IMPLICATION OF THE CONTINUITY OF SAMPLE PATHS

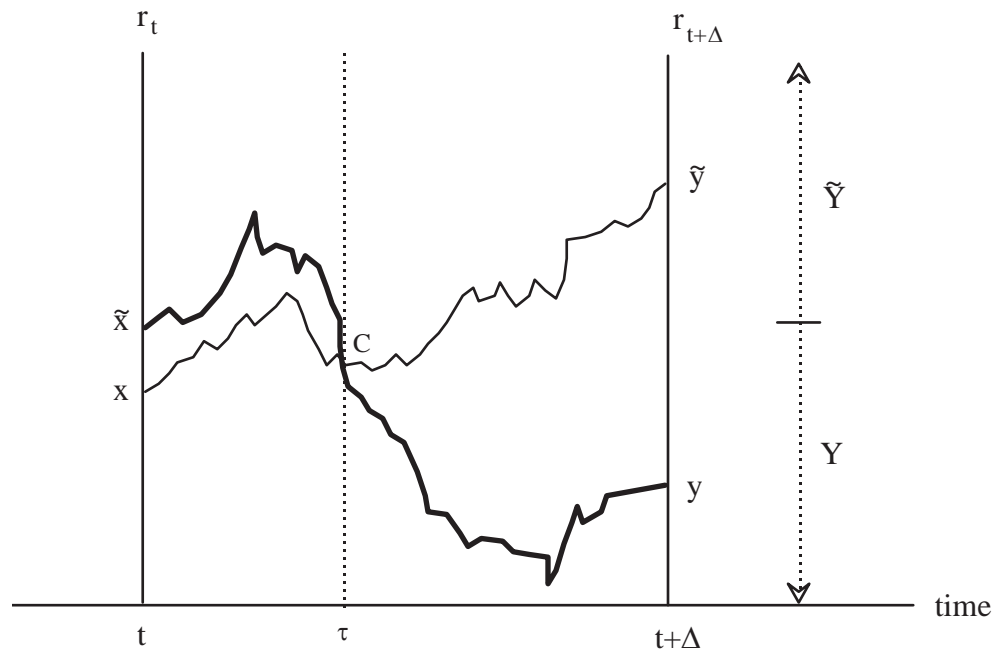


### 3 GEOMETRIC IMPLICATION OF THE CONTINUITY OF SAMPLE PATHS



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- Immediately after they cross, they are indistinguishable by the Markov property and we can interchange them.



- We will see that this simple observation implies that the process is a diffusion if and only if its transition function satisfies:

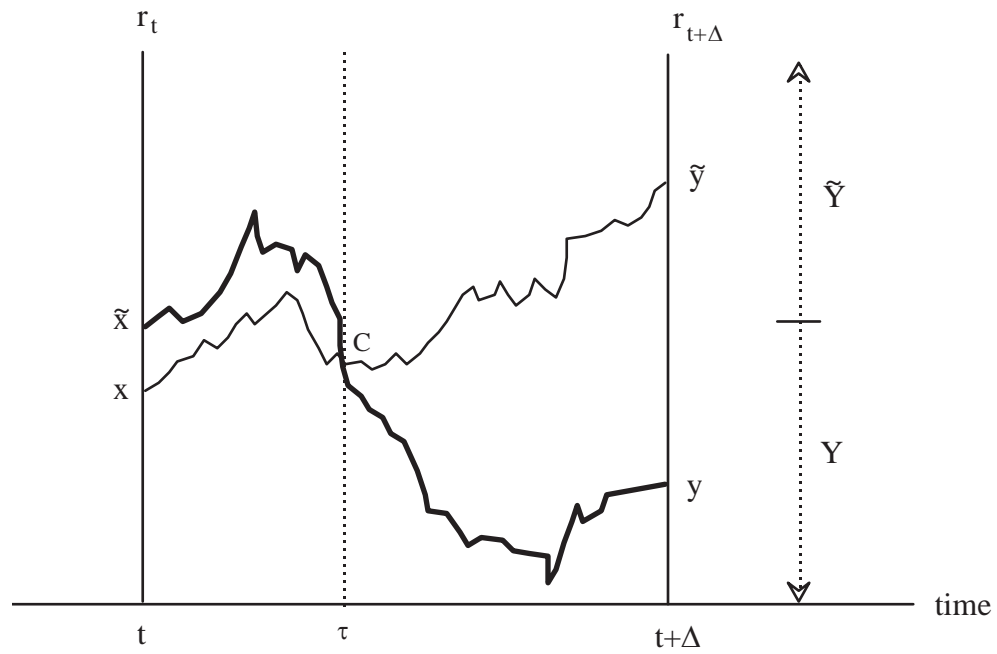
$$\frac{\partial^2}{\partial x \partial y} \ln (p(\Delta, y|x)) > 0$$

- For all  $(x, y)$  and  $\Delta > 0$ . Not just for small  $\Delta$ .

- Sketch of proof of the necessary part
- Consider two sets  $Y$  and  $\tilde{Y}$ , with  $Y < \tilde{Y}$  (meaning each element of  $Y$  and  $\tilde{Y}$  satisfy the inequality).
- Coincidence probability (Karlin and McGregor)

$$\begin{aligned}
 & \Pr \left( r_{t+\Delta} \in Y, \tilde{r}_{t+\Delta} \in \tilde{Y}, \{ \exists s \in [t, t + \Delta] / r_s = \tilde{r}_s \} \mid r_t = x, \tilde{r}_t = \tilde{x} \right) \\
 &= \Pr \left( \tilde{r}_{t+\Delta} \in Y, r_{t+\Delta} \in \tilde{Y}, \{ \exists s \in [t, t + \Delta] / r_s = \tilde{r}_s \} \mid r_t = x, \tilde{r}_t = \tilde{x} \right) \\
 &= \Pr \left( \tilde{r}_{t+\Delta} \in Y, r_{t+\Delta} \in \tilde{Y} \mid r_t = x, \tilde{r}_t = \tilde{x} \right)
 \end{aligned}$$

### 3 GEOMETRIC IMPLICATION OF THE CONTINUITY OF SAMPLE PATHS



- By independence of  $r$  and  $\tilde{r}$ ,

$$\Pr \left( r_{t+\Delta} \in Y, \tilde{r}_{t+\Delta} \in \tilde{Y} | r_t = x, \tilde{r}_t = \tilde{x} \right) = P(\Delta, Y | x) P(\Delta, \tilde{Y} | \tilde{x})$$

$$\Pr \left( \tilde{r}_{t+\Delta} \in Y, r_{t+\Delta} \in \tilde{Y} | r_t = x, \tilde{r}_t = \tilde{x} \right) = P(\Delta, Y | \tilde{x}) P(\Delta, \tilde{Y} | x)$$

where

$$P(\Delta, Y | x) \equiv \int_{y \in Y} p(\Delta, y | x) dx$$

- The probability that  $r_{t+\Delta} \in Y$  and  $\tilde{r}_{t+\Delta} \in \tilde{Y}$  without their sample paths having ever crossed between  $t$  and  $t + \Delta$  is therefore

$$P(\Delta, Y | x) P(\Delta, \tilde{Y} | \tilde{x}) - P(\Delta, Y | \tilde{x}) P(\Delta, \tilde{Y} | x)$$

- Since its a probability, it must be positive.

- Therefore:

$$p(\Delta, y|x) p(\Delta, \tilde{y}|\tilde{x}) > p(\Delta, y|\tilde{x}) p(\Delta, \tilde{y}|x)$$

for all  $x < \tilde{x}$  and  $y < \tilde{y}$  in  $\mathbb{R}$ .

- This is equivalent by taking limits as  $\tilde{y} \rightarrow y$  and  $\tilde{x} \rightarrow x$  to

$$\frac{\partial^2}{\partial x \partial y} \ln(p(\Delta, y|x)) > 0.$$

- The sufficiency part is more involved (see paper).



## 4. Example: SDEs driven by Brownian vs. Cauchy

- Let's distinguish:

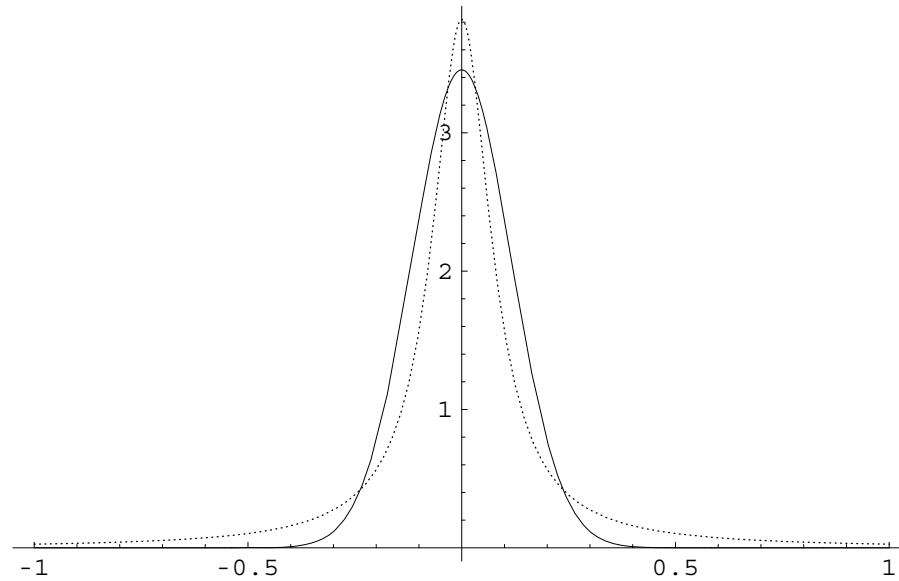
$$dr_t = \beta (\alpha - r_t) dt + \sigma dW_t$$

from:

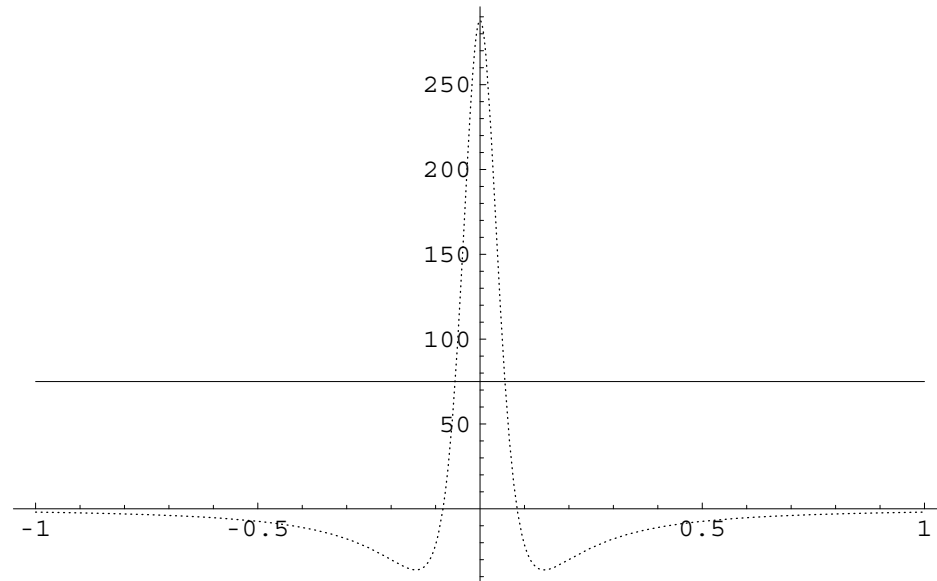
$$dr_t = \beta (\alpha - r_t) dt + \sigma dC_t$$

where  $W$  is a Brownian motion and  $C$  a Cauchy process.

## The two transition functions

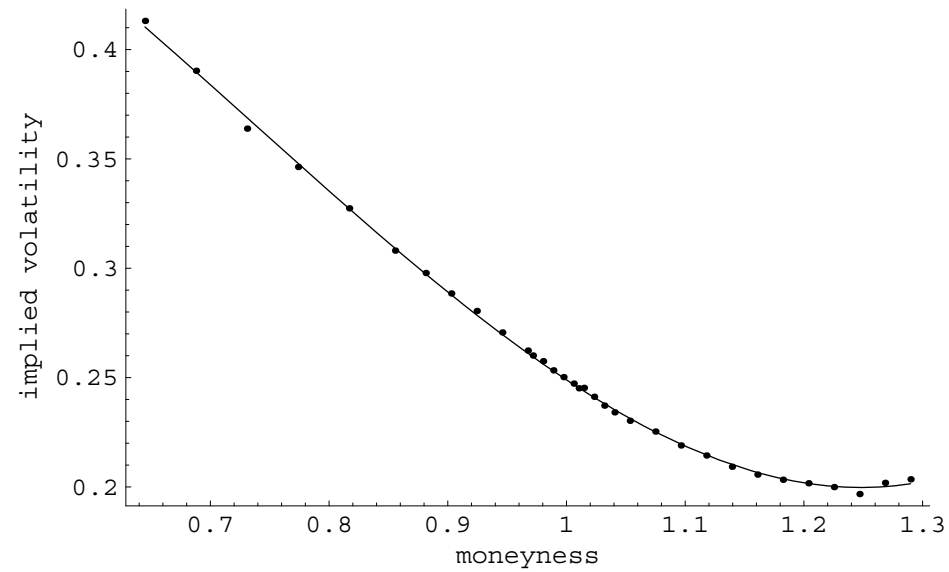


$\frac{\partial^2}{\partial x \partial y} \ln p$  for the two transition functions

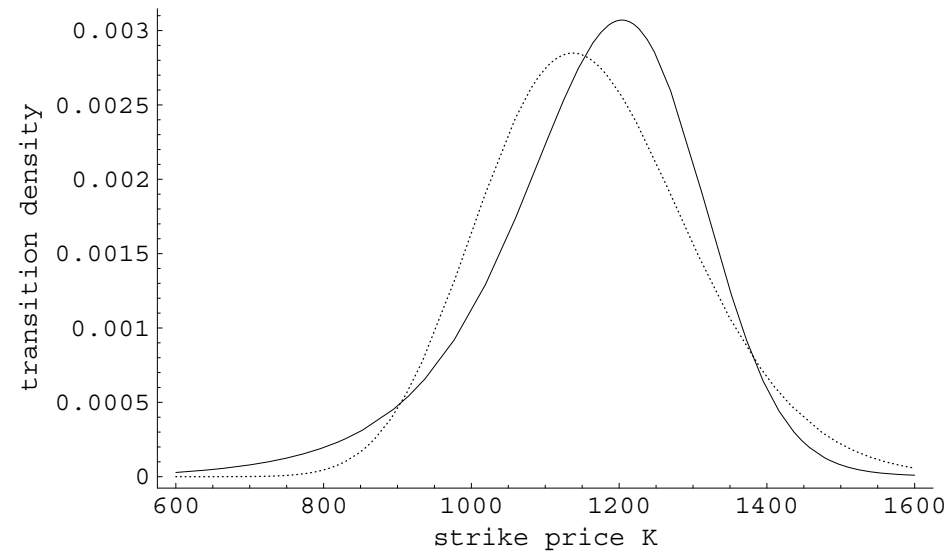


## 5. Empirical Results: SPX Options

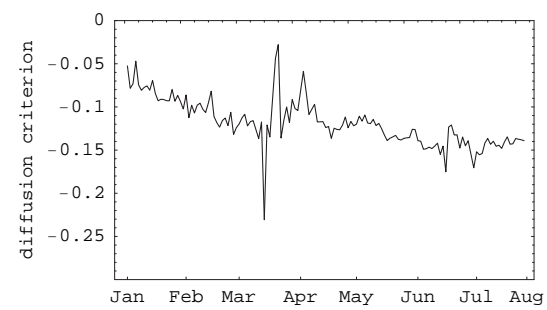
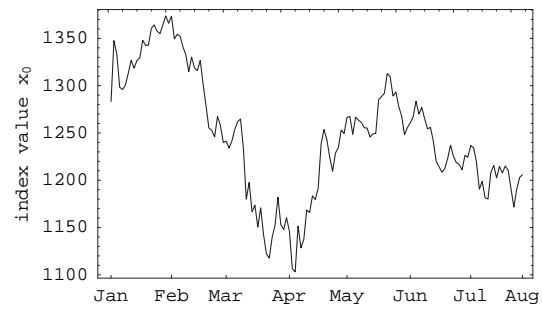
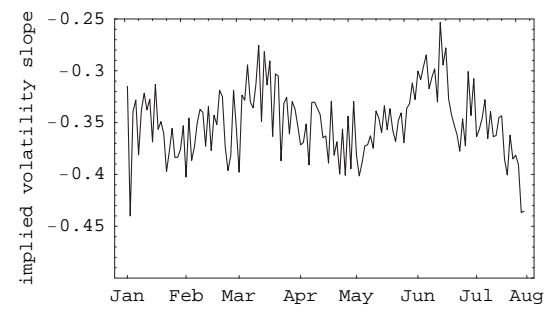
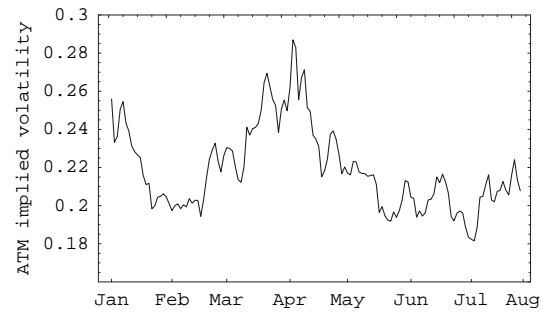
SPX Implied Volatility Smile



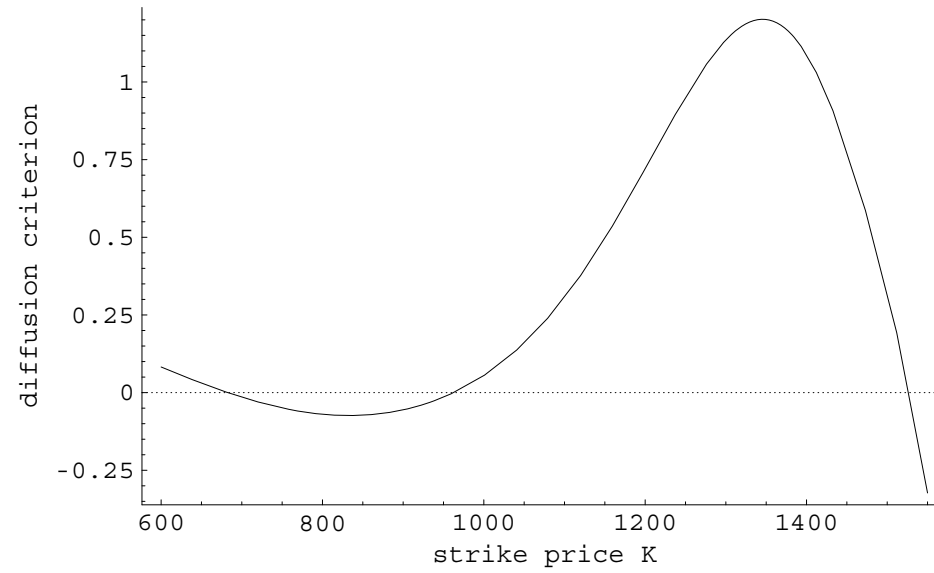
## SPX State-Price Density

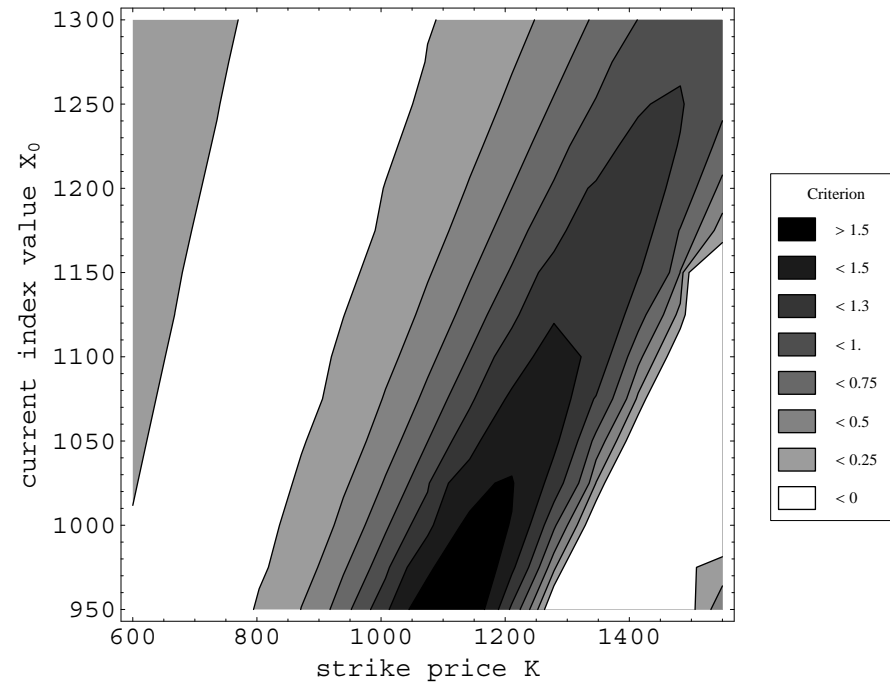


## Time Series



$\frac{\partial^2}{\partial x \partial y} \ln p$  for the data SPX







## 6. Conclusions

- Option prices say jumps are present.
- No need for jumps to be observed, the mere possibility that they happen is sufficient.
- No need for high frequency data.